# Wolfe's Combinatorial Method is Exponential

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joint with Jesús De Loera and Luis Rademacher https://arxiv.org/abs/1710.02608

# **Projection Algorithms for Convex** and Combinatorial Optimization

**Linear Feasibility (LF):** Given a rational matrix A and a rational vector  $\mathbf{b}$ , if  $P_{A,\mathbf{b}} := {\mathbf{x} : A\mathbf{x} \leq \mathbf{b}}$  is nonempty, output a rational  $\mathbf{x} \in P_{A,\mathbf{b}}$ , otherwise output NO.





**Minimum Norm Point (MNP):** Given rational points  $\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_m \in \mathbb{R}^n$ defining  $P := \operatorname{conv}(\mathbf{p}_1, \mathbf{p}_2, \dots, \mathbf{p}_m)$ , output rational  $\mathbf{x} = \operatorname{argmin}_{\mathbf{a} \in P} \|\mathbf{q}\|^2$ .

# Iterative Projection Methods for LF



#### Motzkin's Method (MM)

On Motzkin's Method for Inconsistent Linear Systems (joint with D. Needell) https://arxiv.org/abs/1802.03126

#### Randomized Kaczmarz (RK) Method

Randomized Projection Methods for Corrupted Linear Systems (joint with D. Needell) https://arxiv.org/abs/1803.08114

#### Sampling Kaczmarz-Motzkin (SKM) Methods

 A Sampling Kaczmarz-Motzkin Algorithm for Linear Feasibility (joint with J. A. De Loera and D. Needell)

SIAM Journal on Scientific Computing, 2017 https://arxiv.org/abs/1605.01418

# Wolfe's Combinatorial Methods for MNP

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- $p_3 = p_1$   $p_2 = p_1$   $p_2 = p_2$
- The Minimum Euclidean-Norm Point on a Convex Polytope: Wolfe's Combinatorial Algorithm is Exponential (joint J. A. De Loera and L. Rademacher) STOC, 2018



https://arxiv.org/abs/1710.02608





#### LF:

- ▷ linear programming
- ▷ support vector machine
- ▷ linear equations

#### MNP:

- submodular function minimization
- ▷ colorful linear programming

#### Theorem (De Loera, H., Rademacher '17)

LF reduces to MNP on a simplex in strongly-polynomial time.

# Minimum Norm Point (MNP(P))

We are interested in solving the problem (MNP(P)):

 $\min_{\mathbf{x}\in P} \|\mathbf{x}\|_2$ 

where *P* is a polytope, and determining the minimum dimension face, *F*, which achieves distance  $\|\mathbf{x}\|_2$ .

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Reminder: A *polytope*, *P*, is the convex hull of points  $\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_m$ ,

$$P = \left\{ \sum_{i=1}^{m} \lambda_i \mathbf{p}_i : \sum_{i=1}^{m} \lambda_i = 1, \lambda_i \ge 0 \text{ for all } i = 1, 2, ..., m \right\}.$$

# Minimum Norm Point in Polytope



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# **Minimum Norm Point in Polytope**



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# Minimum Norm Point in Polytope



• arbitrary polytope projection

- arbitrary polytope projection
- nearest point problem for transportation polytopes

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- compute distance to polytope

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It was previously known that linear programming reduces to MNP on a polytope in weakly-polynomial time [Fujishige, Hayashi, Isotani '06].

There exists a family of polytopes on which Wolfe's method requires exponential time to compute the MNP.

Theorem (Wolfe '74) Let  $P = conv(\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_m)$ . Then  $\mathbf{x} \in P$  is MNP(P) if and only if  $\mathbf{x}^T \mathbf{p}_j \ge \|\mathbf{x}\|_2^2$  for all j = 1, 2, ..., m.

#### Wolfe's Optimality Condition

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# Wolfe's Method

# **Philip Wolfe**



- Frank-Wolfe method
- Dantzig-Wolfe decomposition
- simplex method for quadratic programming

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**Def**: An affinely independent set of points  $Q = {\mathbf{q}_1, \mathbf{q}_2, ..., \mathbf{q}_k}$  is a *corral* if MNP(aff(Q))  $\in$  relint(conv(Q)).



**Note**: Singletons are corrals.

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**Note**: There is a corral in P whose convex hull contains MNP(P).
- pivots between corrals which may contain MNP(P)

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- projects onto affine hull of sets to check whether a corral
- optimality criterion checks if correct corral

 $\mathbf{x} \in P = {\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_m}$  $C = \{x\}$ while  $\mathbf{x}$  is not MNP(P)  $\mathbf{p}_i \in {\mathbf{p} \in P : \mathbf{x}^T \mathbf{p} < ||\mathbf{x}||_2^2}$  $C = C \cup \{\mathbf{p}_i\}$  $\mathbf{y} = \mathsf{MNP}(\mathsf{aff}(C))$ while  $\mathbf{y} \notin \operatorname{relint}(\operatorname{conv}(C))$  $\mathbf{z} = \operatorname{argmin} \|\mathbf{z} - \mathbf{y}\|_2$  $z \in \operatorname{conv}(C) \cap \overline{xy}$  $C = C - \{\mathbf{p}_i\}$  where  $\mathbf{p}_i$ ,  $\mathbf{z}$ are on different faces of conv(C) $\mathbf{x} = \mathbf{z}$  $\mathbf{y} = MNP(aff(C))$  $\mathbf{x} = \mathbf{y}$ return x

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 $\begin{aligned} \mathbf{p}_1 &= (0,2) \\ \mathbf{p}_2 &= (3,0) \\ \mathbf{p}_3 &= (-2,1) \end{aligned}$ 



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 $\mathbf{x} \in P = {\mathbf{p}_1, \mathbf{p}_2, ..., \mathbf{p}_m}$  $C = \{x\}$ while  $\mathbf{x}$  is not MNP(P)  $\mathbf{p}_i \in {\mathbf{p} \in P : \mathbf{x}^T \mathbf{p} < ||\mathbf{x}||_2^2}$  $C = C \cup \{\mathbf{p}_i\}$  $\mathbf{y} = \mathsf{MNP}(\mathsf{aff}(C))$ while  $y \notin relint(conv(C))$  $\mathbf{z} = \operatorname{argmin} \|\mathbf{z} - \mathbf{y}\|_2$  $z \in \operatorname{conv}(C) \cap \overline{xy}$  $C = C - \{\mathbf{p}_i\}$  where  $\mathbf{p}_i$ ,  $\mathbf{z}$ are on different faces of conv(C) $\mathbf{x} = \mathbf{z}$  $\mathbf{y} = MNP(aff(C))$  $\mathbf{x} = \mathbf{y}$ return x

$$\mathbf{p}_1 = (0, 2)$$
  
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 $egin{aligned} \mathbf{p}_1 &= (0,2) \ \mathbf{p}_2 &= (3,0) \ \mathbf{p}_3 &= (-2,1) \end{aligned}$ 



15

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$$\mathbf{p}_1 = (0, 2)$$
  
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return x

 $\mathbf{x} = \mathbf{p}_i$  for some  $i = 1, 2, ..., m, \lambda = \mathbf{e}_i$  $C = \{i\}$ while  $\mathbf{x} \neq \mathbf{0}$  and there exists  $\mathbf{p}_i$  with  $\mathbf{x}^T \mathbf{p}_i < \|\mathbf{x}\|_2^2$  $C = C \cup \{j\}$  $\alpha = \operatorname{argmin} \|\sum \alpha_i \mathbf{p}_i\|_2, \ \mathbf{y} = \sum \alpha_i \mathbf{p}_i$  $\sum_{i=1}^{\infty} \alpha_i = 1$   $i \in C$ while  $\alpha_i \leq 0$  for some i = 1, 2, ..., m $\theta = \min_{i:\alpha_i \leq 0} \frac{\lambda_i}{\lambda_i - \alpha_i}$  $\mathbf{z} = \theta \mathbf{y} + (1 - \theta) \mathbf{x}$  $i \in \{j : \theta \alpha_i + (1 - \theta)\lambda_i = 0\}$  $C = C - \{i\}$  $\mathbf{x} = \mathbf{z}$ solve  $\mathbf{x} = P\lambda$  for  $\lambda$  $\alpha = \underset{\sum_{i \in C} \alpha_i = 1}{\operatorname{argmin}} \| \underset{i \in C}{\sum} \alpha_i \mathbf{p}_i \|_2, \ \mathbf{y} = \underset{i \in C}{\sum} \alpha_i \mathbf{p}_i$  $\mathbf{x} = \mathbf{v}$ 

return x

$$\mathbf{x} = \mathbf{p}_i$$
 for some  $i = 1, 2, ..., m$ ,  $\lambda = \mathbf{e}_i$   
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$$C = C \cup \{j\}$$
  
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while  $\alpha_i \leq 0$  for some i = 1, 2, ..., m

$$\theta = \min_{i:\alpha_i \le 0} \frac{\lambda_i}{\lambda_i - \alpha_i}$$
  

$$\mathbf{z} = \theta \mathbf{y} + (1 - \theta) \mathbf{x}$$
  

$$i \in \{j : \theta \alpha_j + (1 - \theta) \lambda_j = 0\}$$
  

$$C = C - \{i\}$$
  

$$\mathbf{x} = \mathbf{z}$$
  
solve  $\mathbf{x} = P\lambda$  for  $\lambda$   

$$\alpha = \underset{\sum_{i \in C} \alpha_i = 1}{\operatorname{solve}} \lim_{i \in C} \alpha_i \mathbf{p}_i \|_2, \ \mathbf{y} = \underset{i \in C}{\sum} \alpha_i \mathbf{p}_i$$
  

$$= \mathbf{y}$$

Choice 1: Initial vertex.

return x

х

$$\mathbf{x} = \mathbf{p}_i$$
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$$\mathbf{x} = \mathbf{y}$$

Choice 1: Initial vertex.

**Choice 2**: Adding to corral.

#### return x

$$\mathbf{x} = \mathbf{p}_i$$
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$$= \mathbf{y}$$

**Choice 1**: Initial vertex.

**Choice 2**: Adding to corral.

**Choice 3**: Removing from corral.

return x

х

• insertion rules have different benefits

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- examples in which each insertion rule is better

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- behavior depends on choice of insertion rule
- examples in which each insertion rule is better
- a dropped vertex may be readded

#### ▷ von Neumann's algorithm for linear programming
- $\triangleright\,$  von Neumann's algorithm for linear programming
- ▷ Frank-Wolfe method for convex programming (and variants)

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▷ Hanson-Lawson procedure for non-negative least-squares

•  $\epsilon$ -approximate solution in  $\mathcal{O}(nM^2/\epsilon)$  iterations with linopt insertion rule (Chakrabarty, Jain, Kothari '14)

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  - > pseudo-polynomial complexity

# **Exponential Behavior**

- dimension and number of points grow linearly

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- number of corrals visited grows exponentially

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### **Recursively Defined Instances**

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+4 points

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dim: d - 2Instance: P(d - 2)Points: 2d - 5  $\xrightarrow{+2 \text{ dim}}$ 

+4 points

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 $P(1) := \{1\}$ 

#### **Recursively Defined Instances**

dim: d - 2Instance: P(d - 2)Points: 2d - 5  $\xrightarrow{+2 \text{ dim}}$ 

+4 points

dim: dInstance: P(d)Points: 2d - 1

 $\begin{array}{l} P(1) := \{1\} \\ P(3) := \{(1, 0, 0), \mathbf{p}_3, \mathbf{q}_3, \mathbf{r}_3, \mathbf{s}_3\} \end{array}$ 

## Exponential Example: dim 3



## **Exponential Example: dim 3**



## **Exponential Example: dim 3**



# Exponential Example

$$P(d) = \begin{pmatrix} P(d-2) & 0 & 0 \\ \frac{1}{2}\mathbf{o}_{d-2}^{*} & \frac{m_{d-2}}{4} & M_{d-2} \\ \frac{1}{2}\mathbf{o}_{d-2}^{*} & \frac{m_{d-2}}{4} & -(M_{d-2}+1) \\ 0 & \frac{m_{d-2}}{4} & M_{d-2}+2 \\ 0 & \frac{m_{d-2}}{4} & -(M_{d-2}+3) \end{pmatrix}$$

$$\begin{split} \mathbf{o}_{d-2}^{*} &: \mathsf{MNP}(P(d-2)) \\ m_{d-2} &= \|\mathbf{o}_{d-2}^{*}\|_{\infty} \\ M_{d-2} &= \mathsf{max}_{\mathbf{p} \in P(d-2)} \, \|\mathbf{p}\|_{1} \end{split}$$

## **Exponential Example**



Consider the execution of Wolfe's method with the minnorm insertion rule on input P(d) where d = 2k - 1. Then the sequence of corrals, C(d) has length  $5 \cdot 2^{k-1} - 4$ .

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1

#### Theorem (De Loera, H., Rademacher '17)

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#### Lemma

Let  $P \subseteq \mathbb{R}^d$  be a finite set of points that is a corral. Let  $\mathbf{x}$  be the minimum norm point in aff P. Let  $\mathbf{q} \in \text{span}\left(\mathbf{x}, \text{span}\left(P\right)^{\perp}\right)$ , and assume  $\mathbf{q}^T \mathbf{x} < \min\{\|\mathbf{q}\|_2^2, \|\mathbf{x}\|_2^2\}$ . Then  $P \cup \{\mathbf{q}\}$  is a corral. Moreover, the minimum norm point  $\mathbf{y}$  in  $\text{conv}(P \cup \{\mathbf{q}\})$  is a (strict) convex combination of  $\mathbf{q}$  and the minimum norm point of P:  $\mathbf{y} = \lambda \mathbf{x} + (1 - \lambda)\mathbf{q}$  with  $\lambda = \mathbf{q}^T(\mathbf{q} - \mathbf{x})/\|\mathbf{q} - \mathbf{x}\|_2^2$ .

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a corral with a point made from MNP and orthogonal directions is still a corral
#### Adding Point to Corral



#### Lemma

Let  $A \subseteq \mathbb{R}^d$  be a proper linear subspace. Let  $P \subseteq A$  be a non-empty finite set. Let  $Q \subseteq A^{\perp}$  be another non-empty finite set. Let **x** be the minimum norm point in aff P. Let **y** be the minimum norm point in aff Q. Let **z** be the minimum norm point in aff $(P \cup Q)$ . We have:

1. **z** is the minimum norm point in  $[\mathbf{x}, \mathbf{y}]$  and therefore  $\mathbf{z} = \lambda \mathbf{x} + (1 - \lambda)\mathbf{y}$  with  $\lambda = \frac{\|\mathbf{y}\|_2^2}{\|\mathbf{x}\|_2^2 + \|\mathbf{y}\|_2^2}$ .

2. If  $\mathbf{x} \neq \mathbf{0}$  and  $\mathbf{y} \neq \mathbf{0}$ , then  $\mathbf{z}$  is a strict convex combination of  $\mathbf{x}$  and  $\mathbf{y}$ .

3. If  $\mathbf{x} \neq \mathbf{0}$ ,  $\mathbf{y} \neq \mathbf{0}$  and P and Q are corrals, then  $P \cup Q$  is also a corral.

#### Lemma

Let  $A \subseteq \mathbb{R}^d$  be a proper linear subspace. Let  $P \subseteq A$  be a non-empty finite set. Let  $Q \subseteq A^{\perp}$  be another non-empty finite set. Let  $\mathbf{x}$  be the minimum norm point in aff P. Let  $\mathbf{y}$  be the minimum norm point in aff Q. Let  $\mathbf{z}$  be the minimum norm point in aff $(P \cup Q)$ . We have:

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#### the union of orthogonal corrals is still a corral

#### **Orthogonal Corrals**



the union of orthogonal corrals is still a corral

#### Lemma

For a point  $\mathbf{z}$  define  $H_{\mathbf{z}} = {\mathbf{w} \in \mathbb{R}^n : \mathbf{w} \cdot \mathbf{z} < ||\mathbf{z}||_2^2}$ . Suppose that we have an instance of the minimum norm point problem in  $\mathbb{R}^d$  as follows: Some points, P, live in a proper linear subspace A and some, Q, in  $A^{\perp}$ . Let  $\mathbf{x}$  be the minimum norm point in aff P and  $\mathbf{y}$  be the minimum norm point in aff $(P \cup Q)$ . Then  $H_{\mathbf{y}} \cap A = H_{\mathbf{x}} \cap A$ .

#### Lemma

For a point  $\mathbf{z}$  define  $H_{\mathbf{z}} = {\mathbf{w} \in \mathbb{R}^n : \mathbf{w} \cdot \mathbf{z} < ||\mathbf{z}||_2^2}$ . Suppose that we have an instance of the minimum norm point problem in  $\mathbb{R}^d$  as follows: Some points, P, live in a proper linear subspace A and some, Q, in  $A^{\perp}$ . Let  $\mathbf{x}$  be the minimum norm point in aff P and  $\mathbf{y}$  be the minimum norm point in aff $(P \cup Q)$ . Then  $H_{\mathbf{y}} \cap A = H_{\mathbf{x}} \cap A$ .

adding orthogonal points to the corral doesn't create any available points

#### Wolfe's Criterion under Addition of Orthogonal Point



Sketch of Proof of Sequence C(d): C(d-2)



$$P(d) = \begin{pmatrix} P(d-2) & 0 & 0\\ \frac{1}{2}\mathbf{o}_{d-2}^{*} & \frac{m_{d-2}}{4} & M_{d-2}\\ \frac{1}{2}\mathbf{o}_{d-2}^{*} & \frac{m_{d-2}}{4} & -(M_{d-2}+1)\\ 0 & \frac{m_{d-2}}{4} & M_{d-2}+2\\ 0 & \frac{m_{d-2}}{4} & -(M_{d-2}+3) \end{pmatrix}$$

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Sketch of Proof of Sequence C(d): C(d-2)



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# Sketch of Proof of Sequence C(d): $O(d-2)\mathbf{p}_d$



Sketch of Proof of Sequence C(d):  $O(d-2)\mathbf{p}_d$ 



a corral with a point made from MNP and orthogonal directions is still a corral

# Sketch of Proof of Sequence C(d): $p_d q_d$



# Sketch of Proof of Sequence C(d): $p_dq_d$



# Sketch of Proof of Sequence C(d): $q_d r_d$



# Sketch of Proof of Sequence C(d): $q_d r_d$



# Sketch of Proof of Sequence $\overline{C(d)}$ : $r_ds_d$



# Sketch of Proof of Sequence C(d): $r_ds_d$



#### Sketch of Proof of Sequence C(d): $C(d-2)r_ds_d$



- the union of orthogonal corrals is still a corral
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# Conclusions

1. Find an exponential example for Wolfe's method with linopt insertion rule.

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- Search for types of polytopes where Wolfe's method is polynomial (e.g. base polytopes).

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- Search for types of polytopes where Wolfe's method is polynomial (e.g. base polytopes).
- 3. Give an average (or smoothed) analysis of Wolfe's method.

# UCDAVIS MATHEMATICS

### Thanks for attending!

# Questions?

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The minimum-norm-point algorithm applied to submodular function minimization and linear programming.

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#### **Example:** minnorm < linopt

$${\mathcal P}={\sf conv}\{(0.8,0.9,0),(1.5,-0.5,0),(-1,-1,2),(-4,1.5,2)\}\subset {\mathbb R}^3$$



Major Cycle	Minor Cycle	С
0	0	$\{p_1\}$
1	0	$\{{\bf p_1},{\bf p_2}\}$
2	0	$\{{\sf p}_1,{\sf p}_2,{\sf p}_3\}$
3	0	$\{{\tt p}_1,{\tt p}_2,{\tt p}_3,{\tt p}_4\}$
3	1	$\{{\tt p_1},{\tt p_2},{\tt p_4}\}$

Major Cycle	Minor Cycle	С
0	0	$\{p_1\}$
1	0	$\{p_1, p_4\}$
2	0	$\{{\sf p}_1,{\sf p}_4,{\sf p}_3\}$
2	1	$\{{\sf p}_1,{\sf p}_3\}$
3	0	$\{{\tt p_1},{\tt p_3},{\tt p_2}\}$
4	0	$\{{\sf p}_1,{\sf p}_2,{\sf p}_3,{\sf p}_4\}$
4	1	$\{{\bf p_1}, {\bf p_2}, {\bf p_4}\}$

Major Cycle	Minor Cycle	С		
0	0	{p <sub>1</sub> }		
1	0	$\{{\tt p_1},{\tt p_2}\}$		
2	0	$\{{\tt p}_1,{\tt p}_2,{\tt p}_3\}$		
3	0	$\{{\tt p}_1,{\tt p}_2,{\tt p}_3,{\tt p}_4\}$		
3	1	$\{{\tt p}_1,{\tt p}_2,{\tt p}_4\}$		
minnorm < linopt				

Major Cycle	Minor Cycle	С
0	0	$\{p_1\}$
1	0	$\{p_1, p_4\}$
2	0	$\{{\sf p}_1,{\sf p}_4,{\sf p}_3\}$
2	1	$\{{\bf p_1},{\bf p_3}\}$
3	0	$\{{\sf p}_1,{\sf p}_3,{\sf p}_2\}$
4	0	$\{{\sf p}_1,{\sf p}_2,{\sf p}_3,{\sf p}_4\}$
4	1	$\{{\sf p}_1,{\sf p}_2,{\sf p}_4\}$